



Ballard Power Systems

**BALLARD**<sup>®</sup>

# **Using Simplorer<sup>®</sup> and Maxwell<sup>®</sup> Tools to Validate Electric Drives for EV Applications, and Interactions with Rapid Prototyping Tools**

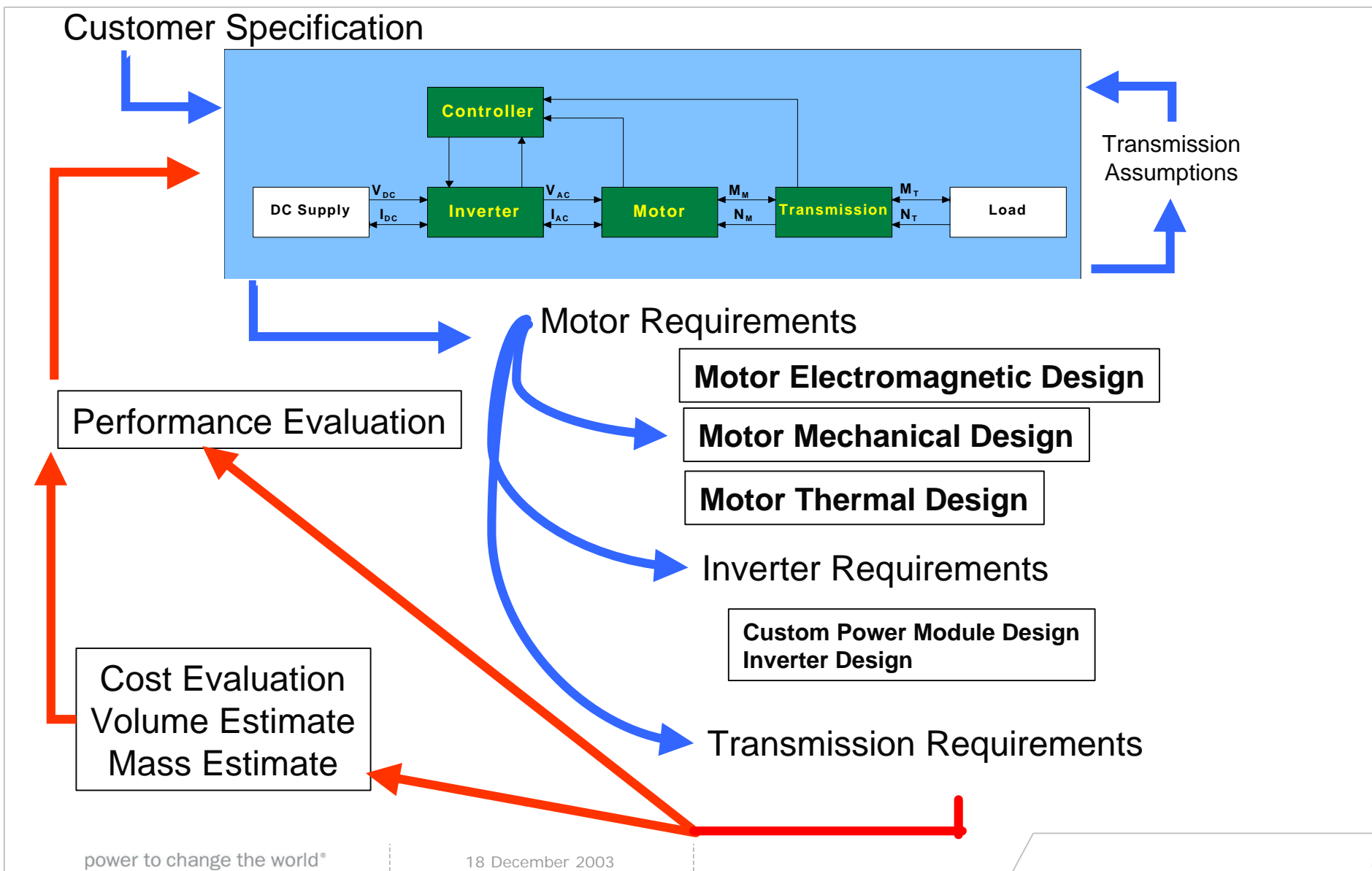
Roy I. Davis  
Ballard Power Systems  
Dearborn, Michigan

Automotive Electromechanical Simulation Workshop  
9 October 2003

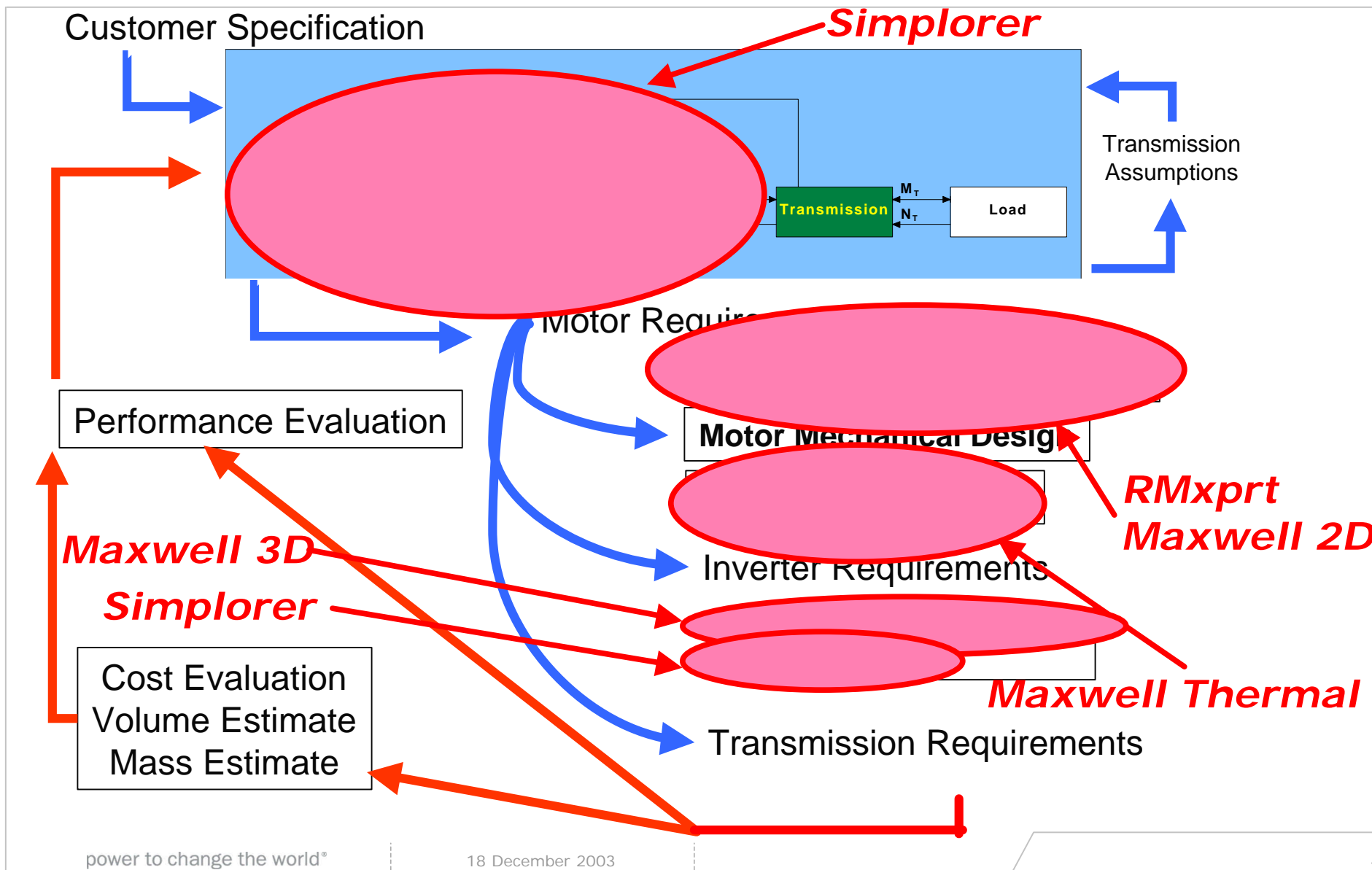
# Electric Drives for EV Applications - Outline

- Brief Overview of Ballard
- Electric Drives Design Process
- How Ansoft Tools Fit In at Ballard
- PM Motor Design Evaluation
- Control Design ↔ Motor Design
- Inverter Design ↔ Custom Power Module Design
- Rapid Prototyping ↔ Control Design
- Testing ↔ Motor Design Evaluation

# Electric Drives Design Process



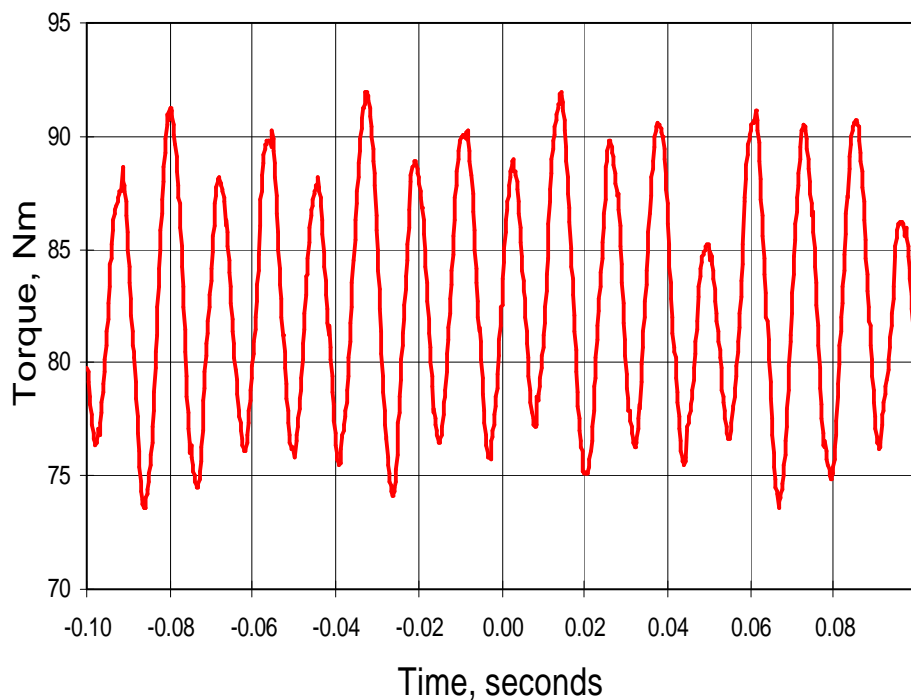
# How Ansoft Tools Fit in at Ballard



# PM Motor Design Evaluation

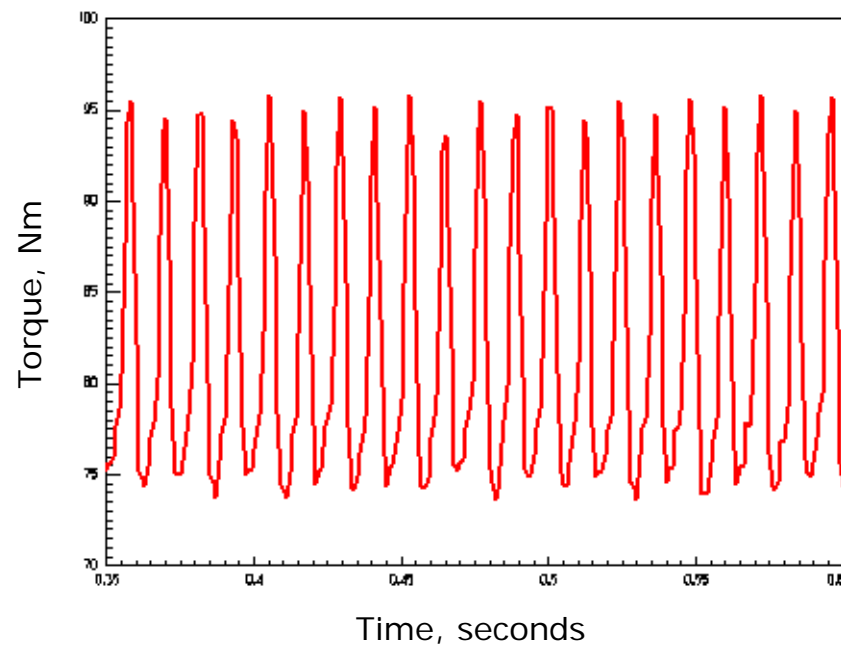
- Maxwell 2D used to perform analysis
  - Calculation of Average Torque and Ripple Torque
    - Average value and peak-to-peak magnitude match well between test and FEA calculations.

Test Data (2.8 revolutions)



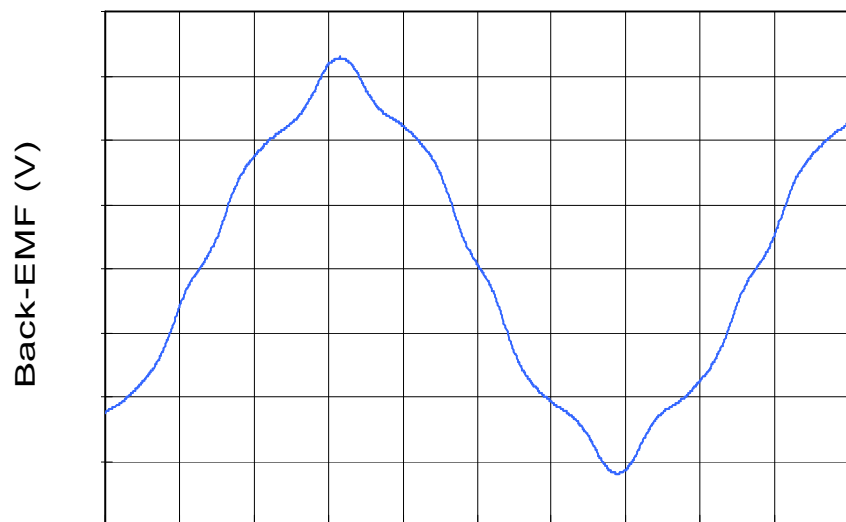
FEA Results (3.7 revs)

Maxwell 2D Torque vs. Time

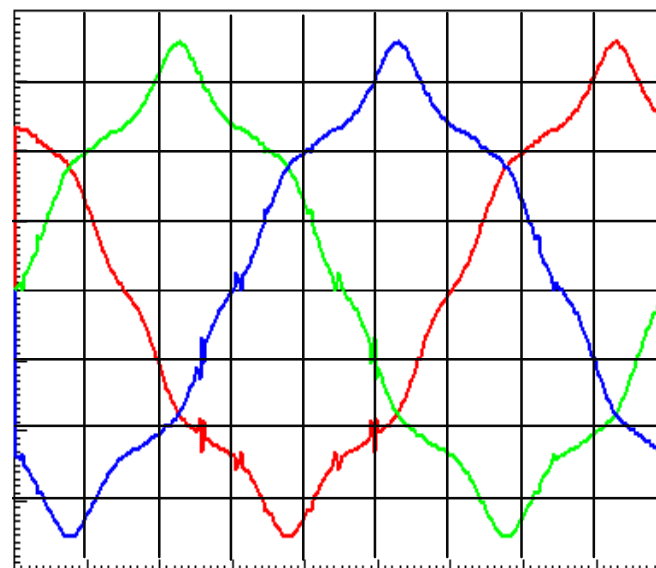


- Maxwell 2D used to perform analysis
  - Calculation of Back EMF
    - Harmonic content and magnitude matches well with experiments.

Test Data



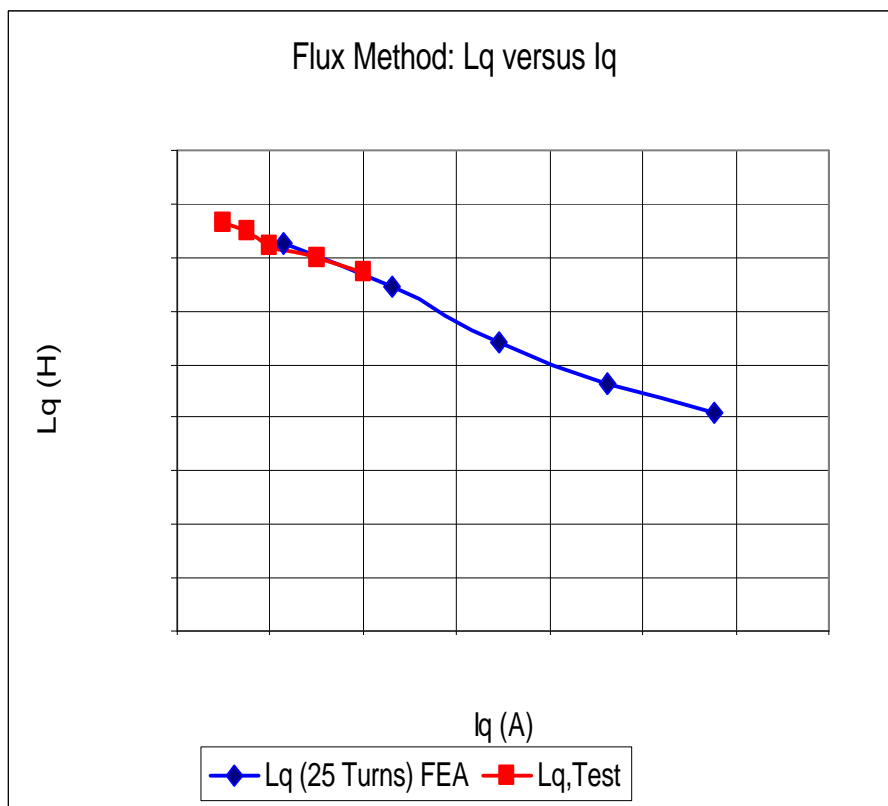
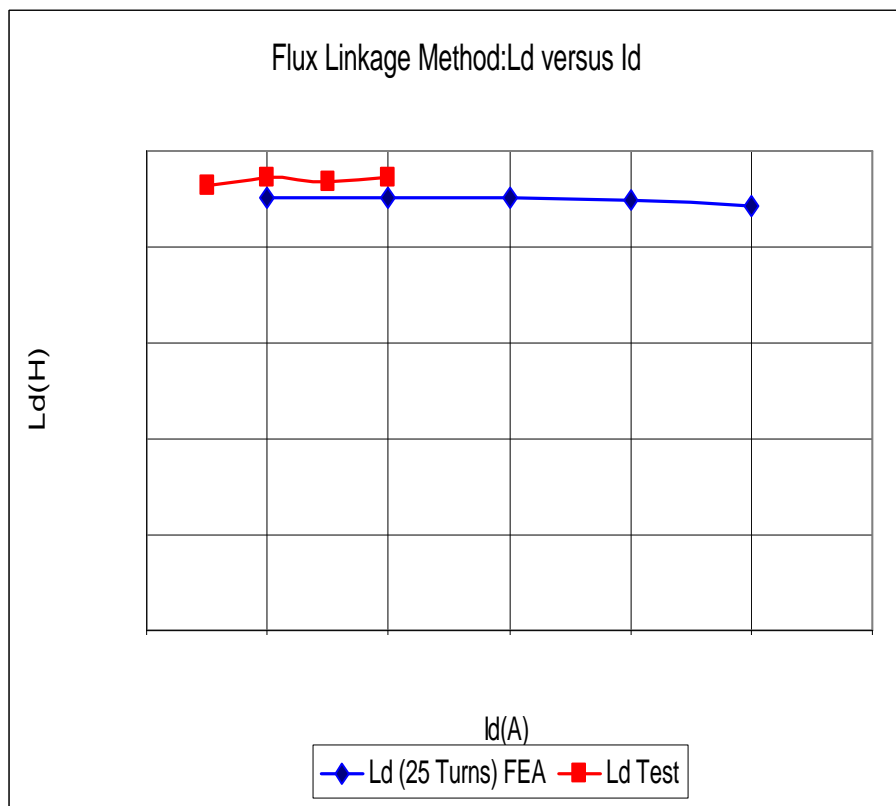
FEA Results



Equal time and voltage scales

# PM Motor Design Evaluation

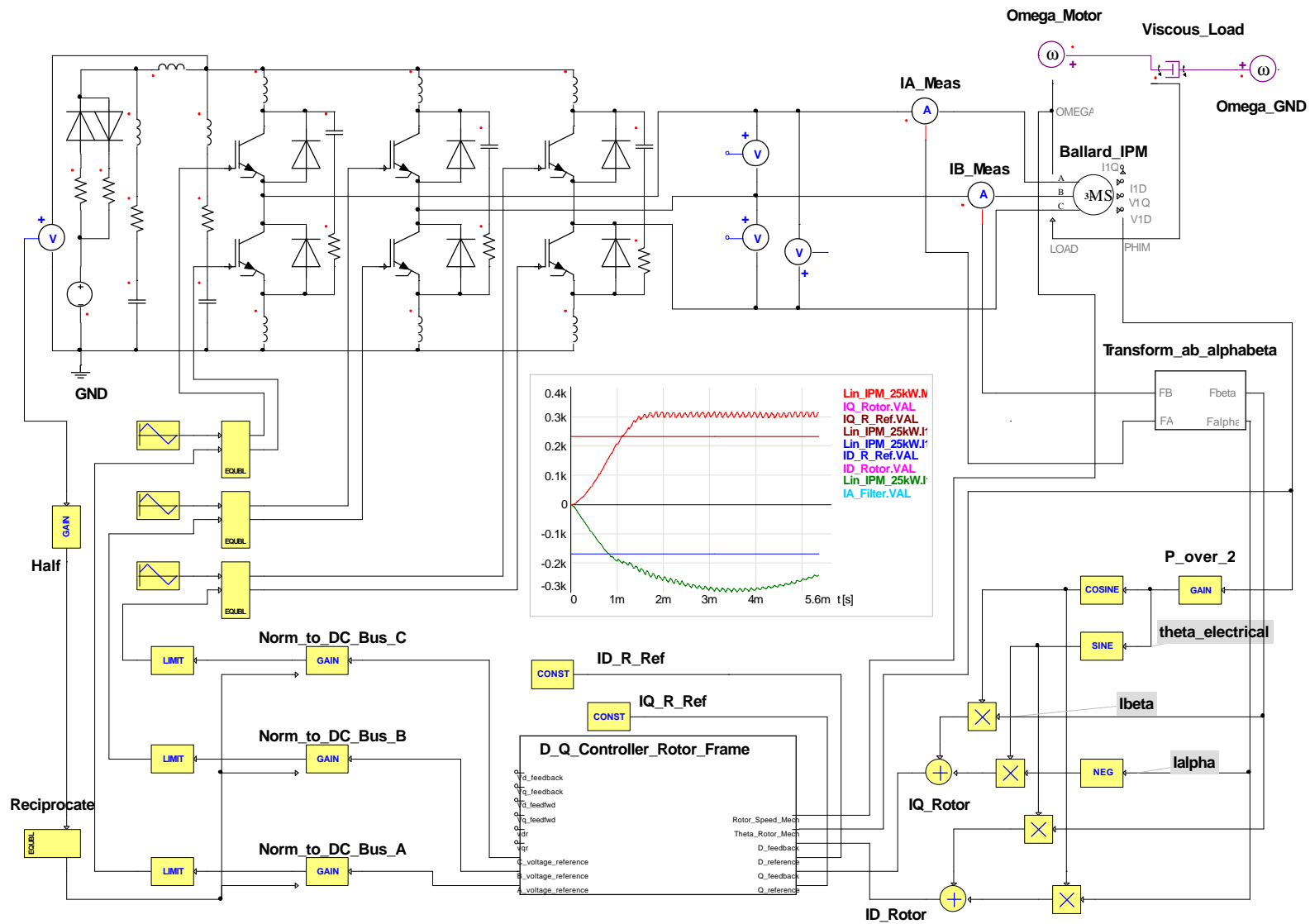
- RMxpert used to enter motor design information
- Maxwell 2D used to perform analysis
  - Calculation of  $L_d$  and  $L_q$  (Energy or Vector Potential Method)



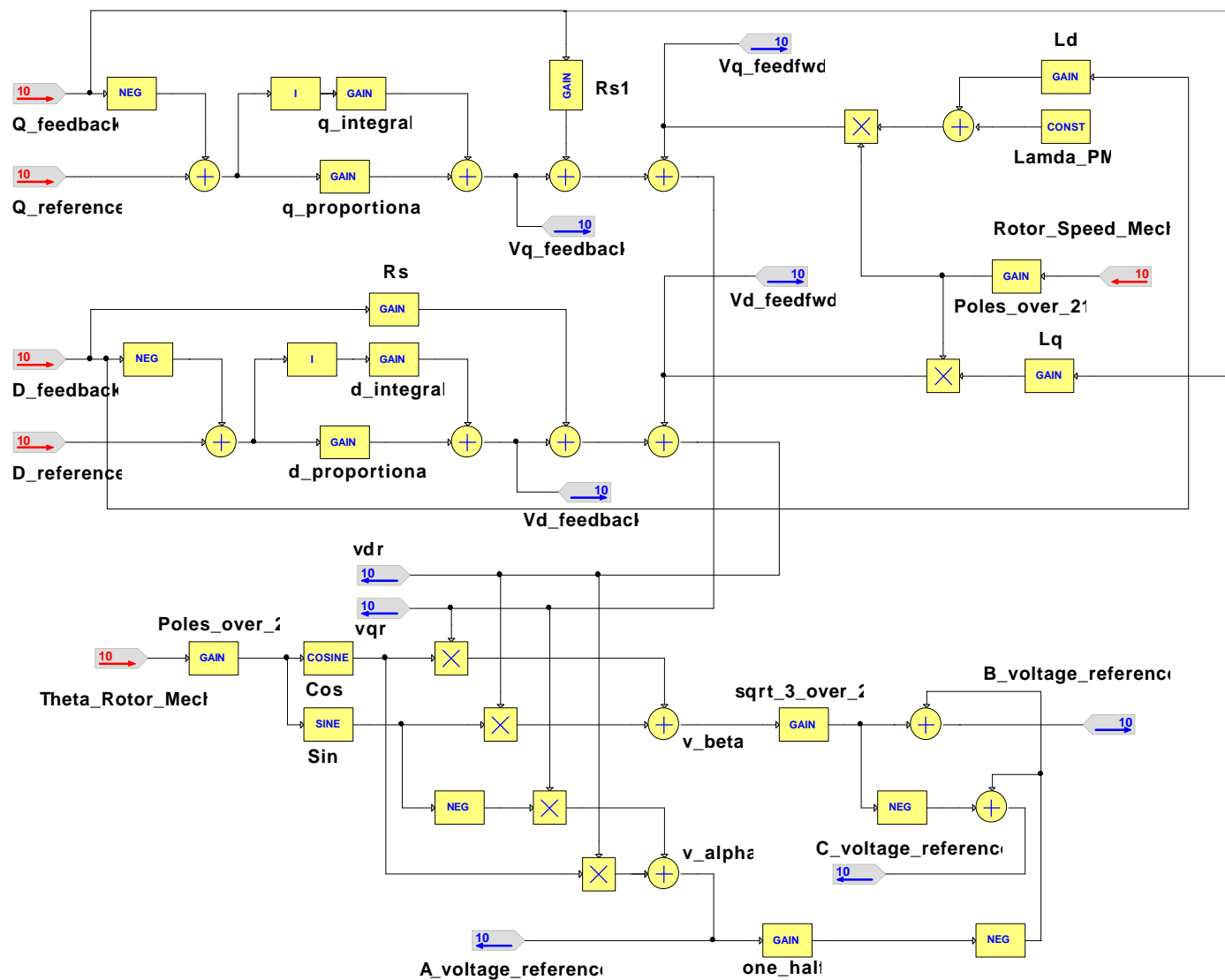
# Control Design ↔ Motor Design - General

- Motor equivalent circuit parameters – with saturation
  - Needed for control development
  - Use Maxwell 2D to update estimates made earlier in design process
  - Used to populate Simplorer model of PM motor
- Ansoft tools are used to explore and understand:
  - PTPA (selection of  $i_d/i_q$  trajectories) – Maxwell & Simplorer
  - Field weakening control – Maxwell & Simplorer
  - Interactions of control with dc bus variations due to load point changes (dynamic) - Simplorer
  - Interactions of sensors and interface limitations on control performance – Simplorer
  - Etcetera
- Matlab/Simulink used as primary control development tool with autocode function for dSpace rapid prototyping hardware.

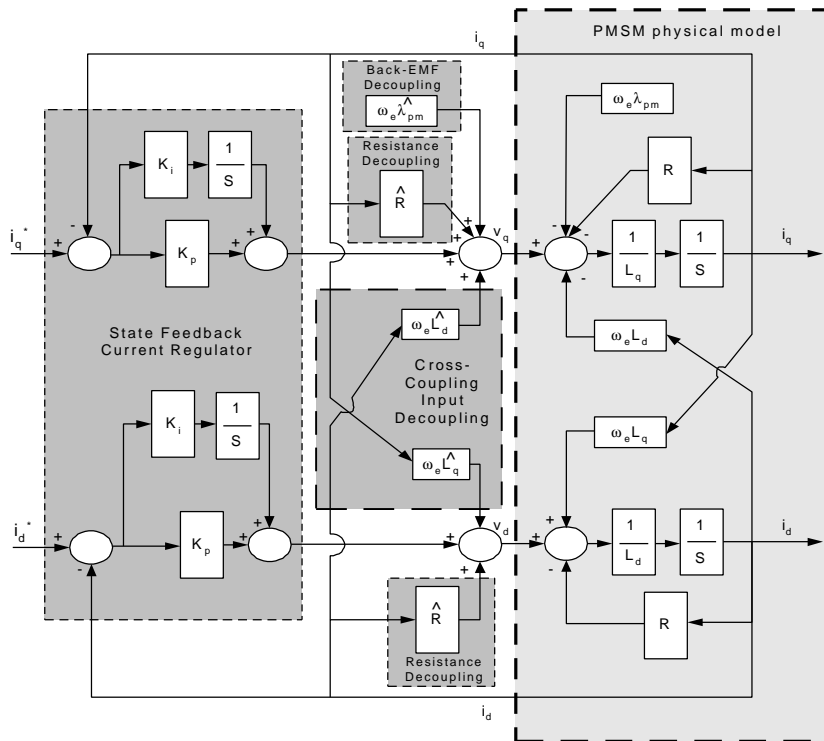
# Control Design ↔ Motor Design - Simplorer



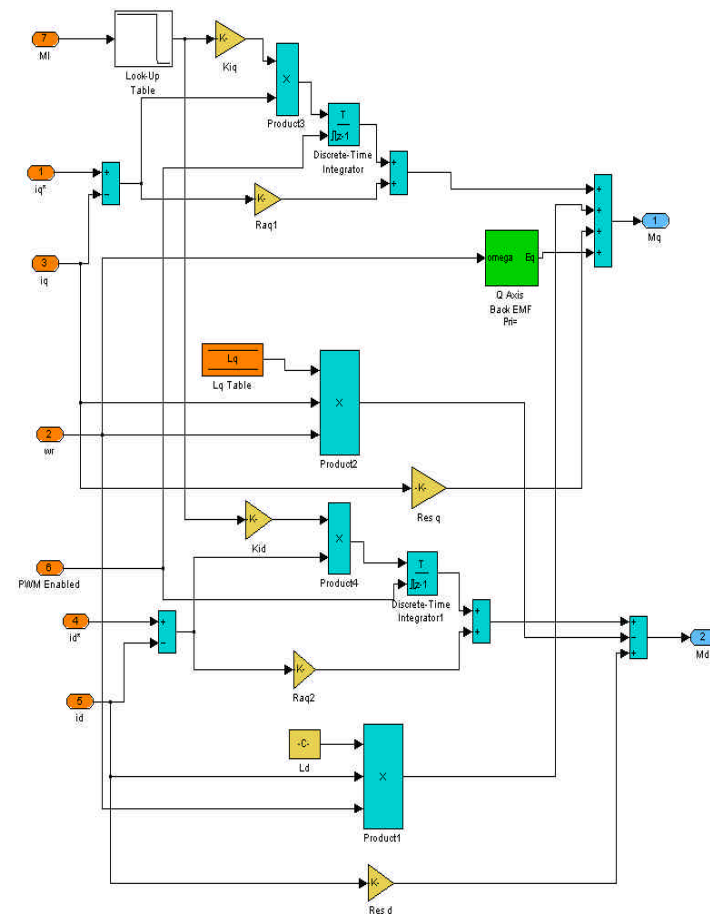
# Control Design ↔ Motor Design - Simplorer



# Control Design ↔ Motor Design – Co-simulate



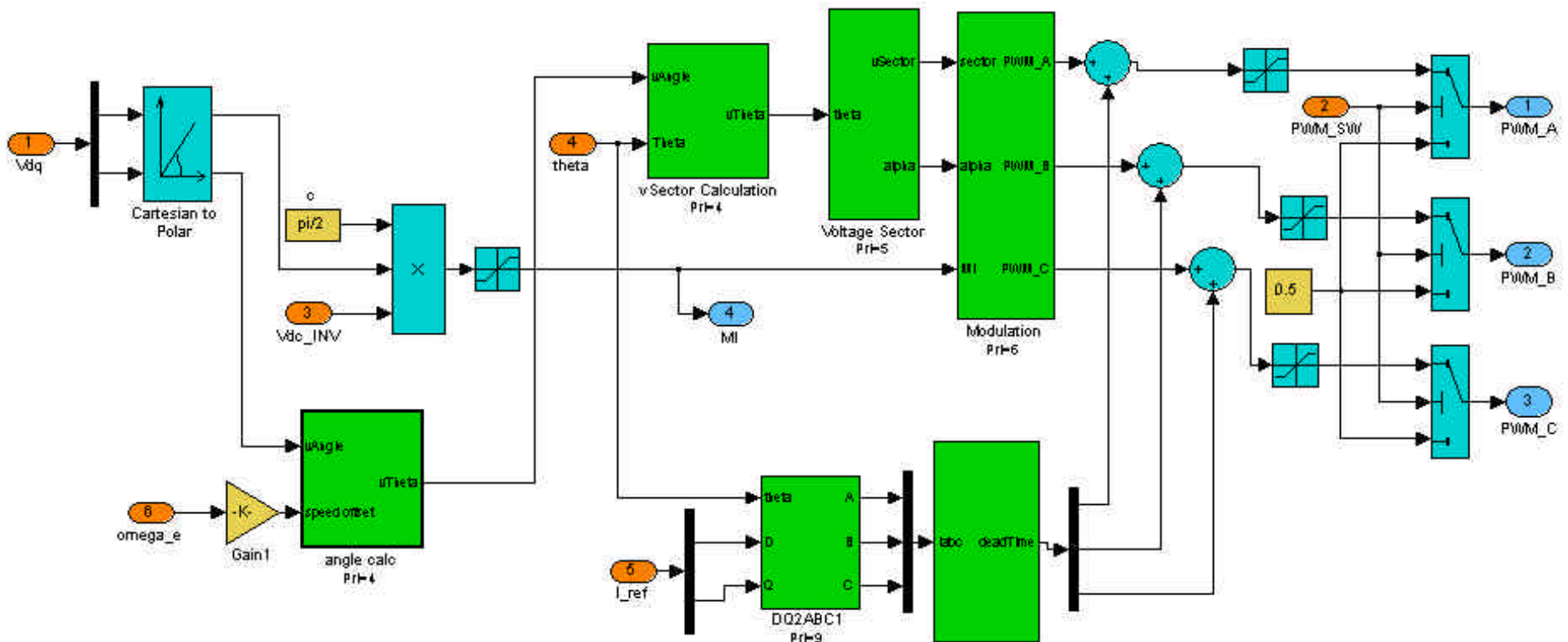
Current Regulator/Motor Block Diagram



Simulink Current Regulator

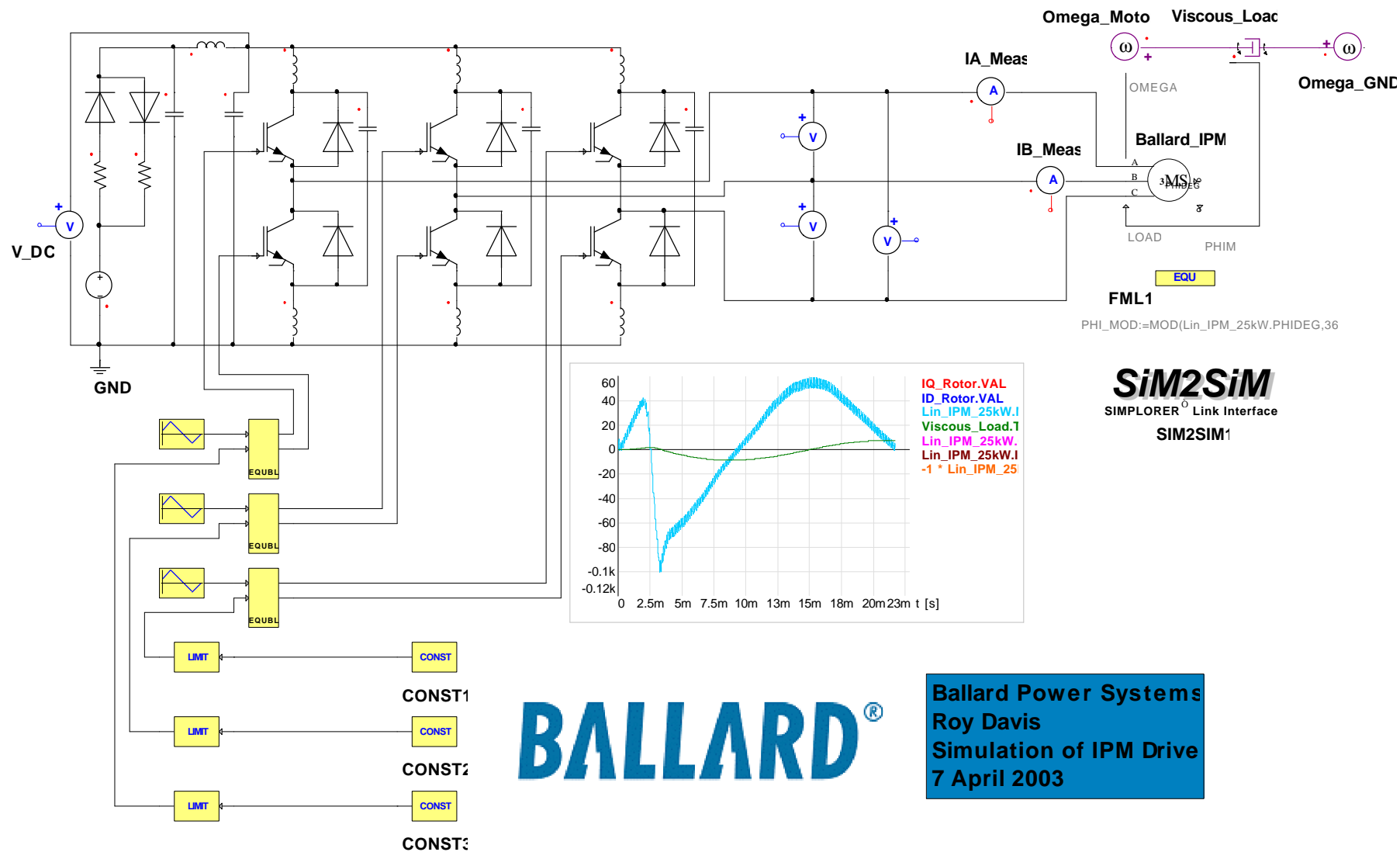
# Control Design ↔ Motor Design – Co-simulate

- Space Vector Modulation (SVM) with Overmodulation Modes 1-2 and Deadtime Compensation



Simulink Model of Modulation Systems

# Control Design ↔ Motor Design – Co-simulate



# Control Design ↔ Motor Design – Co-simulate

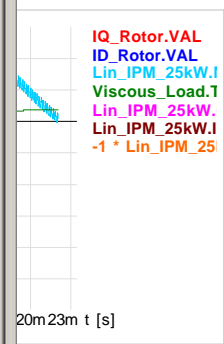
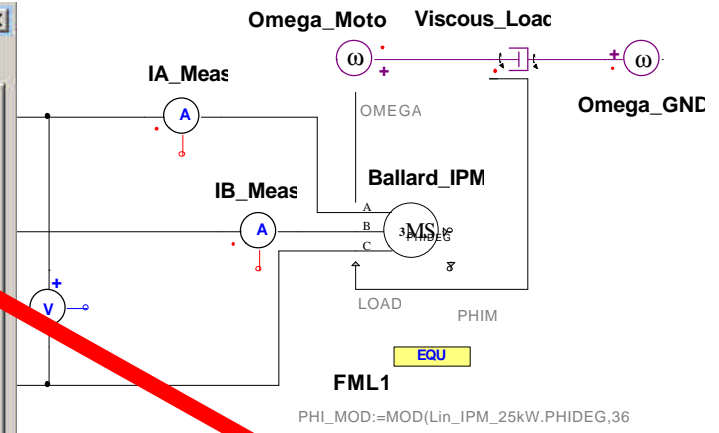
Properties - SIM2SIM1 - Simulink Interface

Link Assignment Dialog Output / Display Library

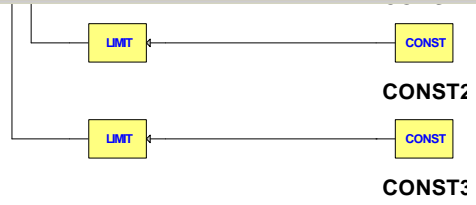
SIMPLORER - IN			SIMPLORER - OUT		
Name	Info	Show	Name	Info	Show
DUTY_A		No display	IA_Meas.I		No display
DUTY_B		No display	IB_Meas.I		No display
DUTY_C		No display	PHI_MOD		No display
			V_DC.V		No display

**SiM2SiM**  
SIMPLORER Link Interface

OK Cancel Apply Help

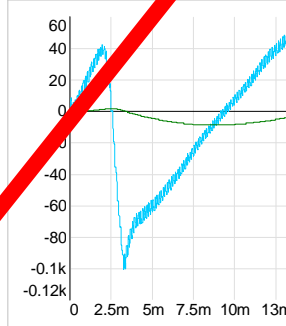
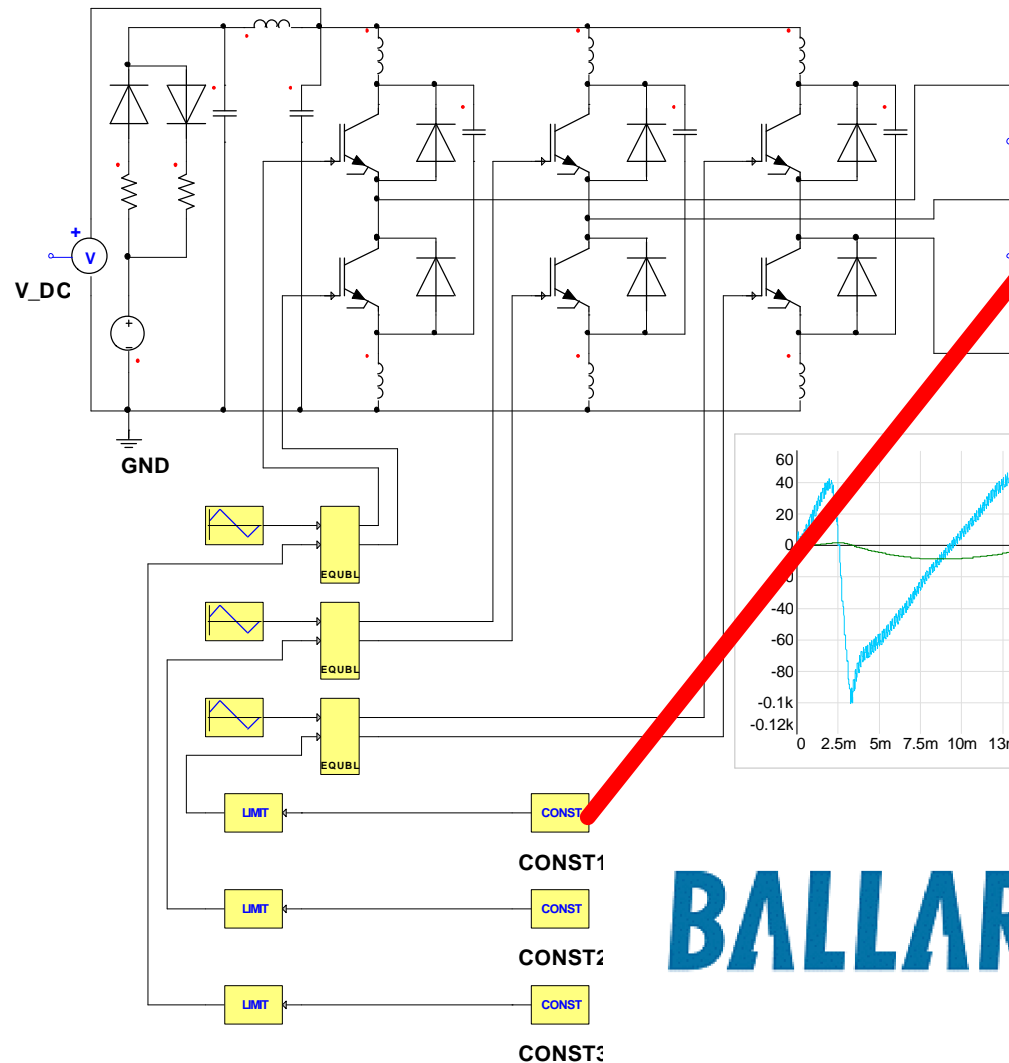


**SiM2SiM**  
SIMPLORER Link Interface  
SIM2SIM1



**Ballard Power Systems**  
Roy Davis  
Simulation of IPM Drive  
7 April 2003

# Control Design ↔ Motor Design – Co-simulate



**Properties - CONST1 - Constant Value**

Parameters | AC - Parameters | Output / Display | Library

Name:   Show Name

Value:   Use Pin

Value, Variable, Expression

Sample Time [s]:   Use Pin

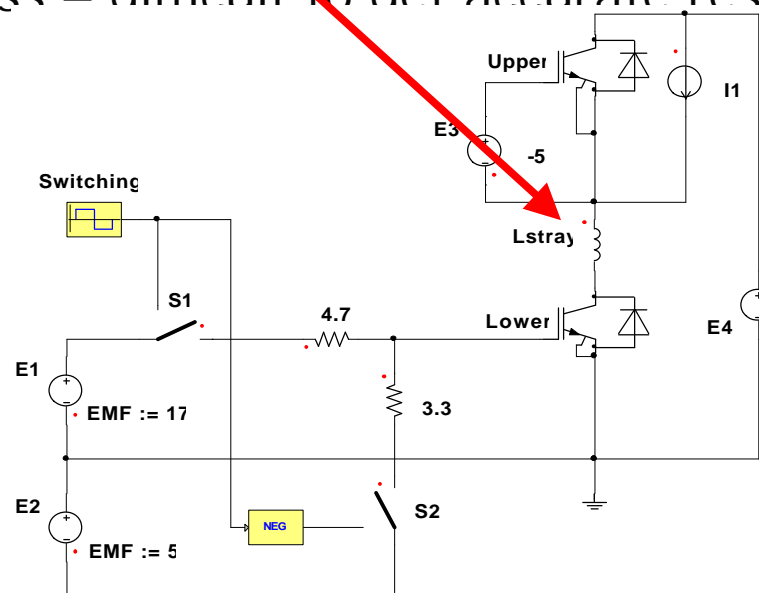
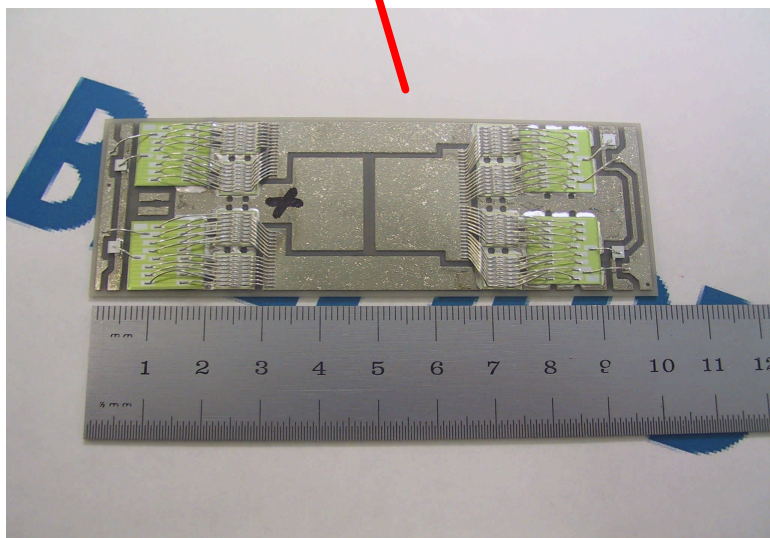
Default Outputs:  Block Output Signal

OK Cancel Apply Help

Ballard Power Systems  
Roy Davis  
Simulation of IPM Drive  
7 April 2003

# Inverter Design ↔ Custom Power Module Design

- Use Maxwell 3D to model power module layout
  - Objective is to compute parasitic module inductance to support module design layout decisions
  - 2<sup>nd</sup> objective is to provide inductances for bridge circuit simulation
  - Presently developing this process – difficult to get accurate results



- Also developing process for parameterizing the detailed models of IGBTs in Simplorer using this test circuit.

# Inverter Design ↔ Custom Power Module Design

- Simpler model of inverter, dc source, and motor used to:
  - Evaluate component stresses under realistic conditions
    - Switches
    - Diodes
    - Capacitors
  - Investigate effects of different/variable PWM algorithms
  - Determine losses

# Rapid Prototyping ↔ Control Design

- We use dSpace for rapid prototyping control design and motor performance evaluations on the dyno
  - Clean interface to Simulink/RTW with Control Desk
- Simpler model of motor and inverter easily integrated with Simulink model of control
  - Helps to debug any problems arising from interactions with inverter
  - PM motor model easily allows use of saturable inductances as functions of current
  - Easy to do what-if investigations
  - Much easier and seemingly more reliable than Matlab Power System Toolbox to include detail model of inverter and PM motor.

# Testing ↔ Motor Design Evaluation

- Unexplained or different behavior that occurs during testing can be examined in Maxwell or Simplorer to determine cause.
- Provides a feedback link to design tool usage that allows refinement of “rules of thumb” or development of design rules to be applied with the numerical design tools.

